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| We seek applicants who will provide leadership, develop innovative courses, and perform research in promising new topics in control and estimation. We invite applications from qualified candidates for one Tenured Position in the area of Guidance, Navigation, and Control (senior Associate Professor or Full Professor). Research topics may include, but are not limited to: advanced estimation, hybrid control, multi-vehicle control, autonomous systems, and cyber-physical systems, with applications to manned and unmanned aerospace vehicles. Applicants for this position are expected to have a doctoral degree in engineering or equivalent and to have an established extramurally-funded research program, with a strong publication record and excellence in teaching The successful candidate for this position is expected to supervise graduate students, teach undergraduate and graduate courses, develop sponsored research programs, collaborate with other faculty, and be involved in service to the university and the engineering profession. Applications received by December 31, 2011 are assured full consideration, but the search will continue until this position is filled. To apply submit an application online at the link provided; only complete applications will be considered.  |