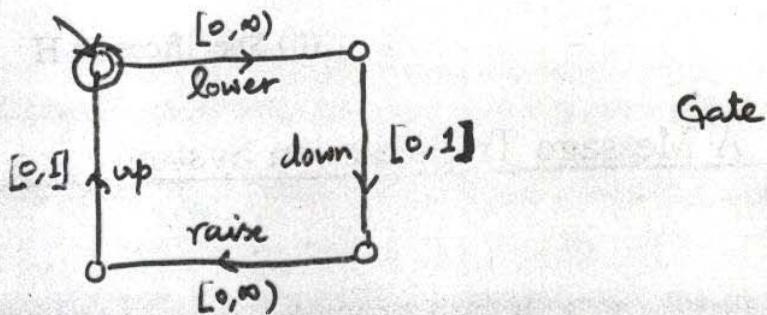
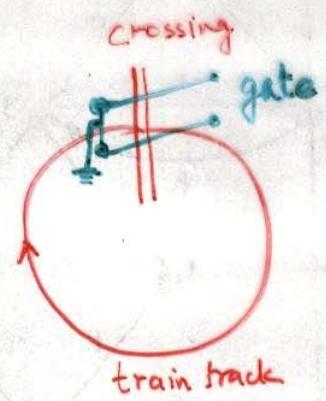
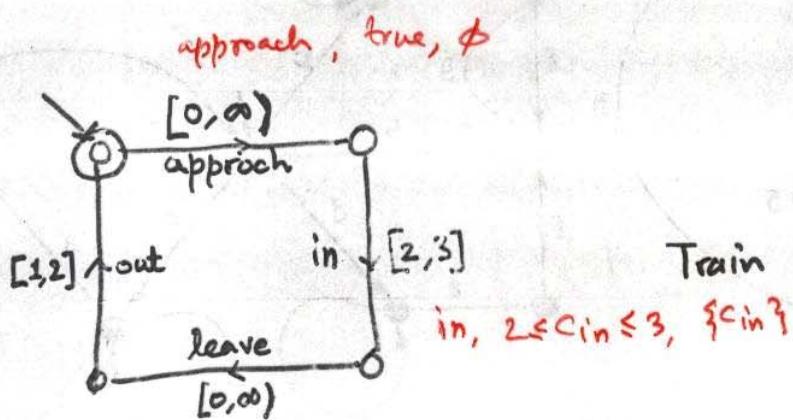


Train-Gate Example



- $P = \text{train} \parallel \text{gate}$
- Desired timed traces : $K \subseteq T^m(P)$
 - train in \Rightarrow gate down
 - gate up within 5 time units of train leaving
- Uncontrollable events : approach, in, out, down, up
- Unobservable events : in, down, up

$\Sigma_u = \text{sensor} + \text{failure events}$

$\Sigma_o = \text{sensor} + \text{actuator events}$
↳ synchronization requirements