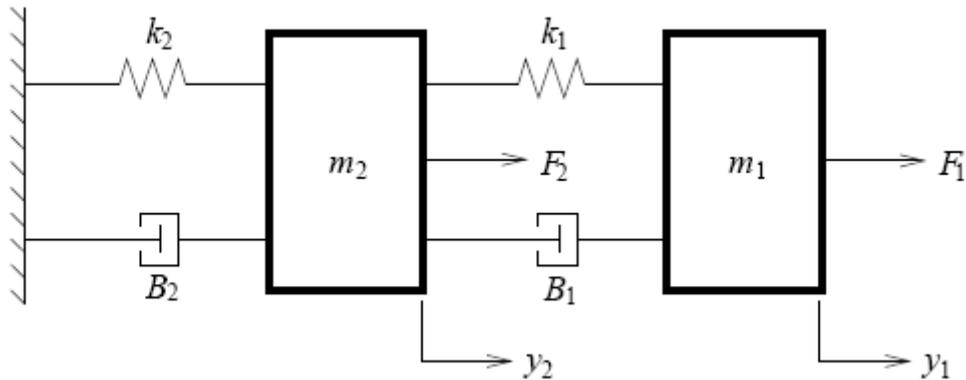


Consider the mass-spring-damper system of the figure below.



1. Write down the differential equation model. (There will be two equations, one for each mass. The system has two inputs F_1 and F_2 , and two outputs are y_1 and y_2 . Note that m_1 has three forces acting on it, whereas m_2 has five.)
2. Draw the simulink model of the mass-spring-damper system.
3. For each of the two inputs and for each of the 4 parameter values given below plot y_1 and y_2 for time 0 to 60secs.

Inputs:

- a. F_1 is step, F_2 is zero
- b. F_2 is step, F_1 is zero

Parameters:

- a. $m_1=m_2=K_1=K_2=B_1=B_2=1$
- b. $m_1=m_2=K_1=K_2=1, B_1=B_2=10$
- c. $m_1=m_2=10, K_1=K_2=1, B_1=B_2=1$
- d. $m_1=m_2=10, K_1=K_2=1, B_1=B_2=10$