

## **Review--Exam 3**

### **Mechanism Design**

Distinction between path and motion generation  
Vector equations required for solution to left and right dyads  
Knowing how to solve for unknowns  
Knowing which parameters are given, which ones are to be solved for  
How do you verify the motion of the device?  
What are some quality measures of a designed 4-bar?

### **Kinematics**

Being able to draw a skeleton  
Using proper conventions on angles  
Being able to determine what is known and what is to be solved for  
Knowing how to solve for position, velocity and acceleration unknowns  
Knowing how to compute the position, velocity and acceleration of any point on a device.

### **Cams**

Understanding the advantages and disadvantages of constant acceleration, SHM, cycloidal cam profiles

Cam terminology

- pressure angle
- base circle
- prime circle
- pitch curve
- cam profile
- cam coordinates
- radius of curvature
- undercutting

Being able to compute pressure angle, radius of curvature,  $s$ ,  $s'$ ,  $s''$ ,  $s'''$   
What is jerk? What is its significance?