

## Rules of Thumb for Shaft Design

- Keep shafts as short as possible
- Bearings should be close to applied loads
- Place any stress risers away from highly stressed regions of the shaft (local strengthening at risers may be helpful)
- Consider hollow shafts when weight is critical (weight to stiffness ratio should be low)
- For deflection concerns, choose a low carbon steel (why?)
- The first natural frequency of the shaft should be three times as high as the highest forcing frequency expected in service.

## Design of Shafts based on loading modes

*Fully reversed bending and constant Torsion*

Shear stress due to torsion is steady—there will be a **mean component of shear, but not an alternating component of shear**

$$\begin{aligned}T_{\max} &= T_{\min} = T \\t_m &= \frac{T_{\max} \frac{d}{2}(32) + T_{\min} \frac{d}{2}(32)}{Pl^4} \\&= \frac{T(16) + T(16)}{Pl^3} = \frac{32T}{Pl^3} \\t_a &= \frac{T_{\max} \frac{d}{2}(32) - T_{\min} \frac{d}{2}(32)}{Pl^4} \\&= 0\end{aligned}$$

Stresses due to bending will yield an **alternating component, but not a mean moment**—see if you can convince yourself of this.

## Designing Shafts for Fully Reversed Bending and Steady Torsion

The failure envelope for reversed bending and static torsion for test specimens is given by the following relationship:

$$\left(\frac{s_a}{S_e}\right)^2 + \left(\frac{t_m}{S_{ys}}\right)^2 = 1$$

Include a factor of safety,  $N_f$

$$\left(N_f \frac{s_a}{S_e}\right)^2 + \left(N_f \frac{t_m}{S_{ys}}\right)^2 = 1$$

$$S_{ys} = \frac{S_y}{\sqrt{3}}$$

$$\left(N_f \frac{s_a}{S_e}\right)^2 + \left(N_f \frac{\sqrt{3}t_m}{S_y}\right)^2 = 1$$

$$s = K_f \frac{32M}{\pi d^3}$$

$$t_m = K_{fs} \frac{16T_m}{\pi d^3}$$

$$\left(N_f \frac{K_f \frac{32M_a}{\pi d^3}}{S_e}\right)^2 + \left(N_f \frac{\sqrt{3}K_{fs} \frac{16T_m}{\pi d^3}}{S_y}\right)^2 = 1$$

Solve for d.